

Specification of the Measurement of the Luminosity (and Backgrounds?)

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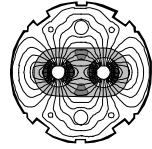
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Functional Specification

MEASUREMENT OF THE LUMINOSITY AND BACKGROUNDS AT THE LHC

Abstract

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S Myers for LCC, H. Schmickler, R. Jung, E. Bravin, W. Herr, J.B. Jeanneret, B. Turner, K. Potter, D. Macina, M. Bozzo, K. Eggert, representatives of the LHC experiments,...

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Scope:

- 1) Overall view of the luminosity/background issue
- 2) **Specification of the machine instruments**
(Luminometer, background monitors?)

Observables:

- 1) Counting rates of collision products
- 2) Beam-beam electro-magnetic coupling (beam-beam scan: L, orbit, ... vs b-b offset)

Derived info: (parameters)

- 1) Absolute and relative luminosity
- 2) Transverse residual separation of the colliding bunches
- 3) Position of the vertex in 3D space
- 4) Crossing angle
- 5) IP spot sizes of bunches
- 6) `Standard' background rates (?)

Peak luminosity:

Two independent LHC beams...

$$\mathcal{L} = \frac{N_{b1} N_{b2} f_{rev} k_b}{2\pi \sqrt{(\sigma_{x1}^2 + \sigma_{x2}^2)(\sigma_{y1}^2 + \sigma_{y2}^2)}} \cdot \exp \left\{ -\frac{(\bar{x}_1 - \bar{x}_2)^2}{2(\sigma_{x1}^2 + \sigma_{x2}^2)} - \frac{(\bar{y}_1 - \bar{y}_2)^2}{2(\sigma_{y1}^2 + \sigma_{y2}^2)} \right\}$$

Optimize peak luminosity:

Increase

bunch intensities
number of bunches

Decrease

beam-beam offsets
beam sizes at IP's

Strategy & Responsibilities

- It is the **responsibility of the experiments to measure their own luminosity**.
- **Standardized, simple, fast and robust machine luminometers** are necessary to set-up the machine for physics, optimize, compare from run to run... Most used: Relative measurement (maximize). The absolute luminosity may be calibrated for cross-checks (equalize luminosity performance).
- **Background** to the experiments:
 - It is an issue for LHC
 - Experience (ISR) shows that standard background monitors have been very helpful. What about LHC?
 - Could be provided by the physics community

Beam & Machine Conditions

1. Running scenarios

2. Range of beam parameters

Initial peak luminosity

Luminosity decay

Expected background rates

Ions

3. Range of machine conditions

Example scenarios to define range in luminosities

Commissioning scenario

*Low resolution
signal desirable*

First collisions at 7 TeV, 1 on 1, pilot intensity, injection optics (large IP spot size). Set up IP's.

7 TeV collisions, 1 on 1, pilot intensity, squeezed optics (smaller IP spots size). Set up IP's.

7 TeV collisions, 1 on 1 or few on few, nominal intensity. Set up luminosity.

Initial running

Nominal running

Ultimate running

*Required to measure
with good resolution
(L and time)*

Bunch population	Number of bunches	Bunch spacing	Mode	Experiment (not exclusive)	IP beta	Luminosity [cm ⁻² s ⁻¹]
<i>(a) Collisions studies with single pilot bunch</i>						
5×10 ⁹	1	n/a	p-p	ATLAS/CMS	18 m	2.0×10 ²⁶
5×10 ⁹	1	n/a	p-p	ATLAS/CMS	0.5 m	7.2×10 ²⁷
5×10 ⁹	1	n/a	p-p	ALICE	10 m	3.6×10 ²⁶
5×10 ⁹	1	n/a	p-p	LHC-b	35 m	1.0×10 ²⁶
<i>(b) Collision studies with single high intensity bunch</i>						
2.75×10 ¹⁰	1	n/a	p-p	ATLAS/CMS	0.5 m	8.7×10 ²⁹
1.1×10 ¹¹	1	n/a	p-p	ATLAS/CMS	18 m	9.9×10 ²⁸
1.1×10 ¹¹	1	n/a	p-p	ATLAS/CMS	0.5 m	3.6×10 ³⁰
1.1×10 ¹¹	1	n/a	p-p	ALICE	10 m	1.8×10 ²⁹
1.1×10 ¹¹	1	n/a	p-p	LHC-b	35 m	5.1×10 ²⁸
<i>(c) Early p-p luminosity run (different scenarios)</i>						
2.75×10 ¹⁰	1260	50 ns	p-p	ATLAS/CMS	0.5 m	1.1×10 ³³
2.75×10 ¹⁰	2520	25 ns	p-p	ATLAS/CMS	0.75 m	1.5×10 ³³
1.1×10 ¹¹	936	75 ns	p-p	ATLAS/CMS	0.75 m	2.2×10 ³³
<i>(d) Nominal p-p luminosity run</i>						
1.1×10 ¹¹	2808	25 ns	p-p	ATLAS/CMS	0.5 m	1.0×10 ³⁴
				LHC-B	35 m	1.0×10 ³²
				ALICE [1]	10 m	1.0×10 ³⁰
<i>(e) Ultimate p-p luminosity run</i>						
1.7×10 ¹¹	2808	25 ns	p-p	ATLAS/CMS	0.5 m	3.0×10 ³⁴
<i>(f) TOTEM runs</i>						
1.1×10 ¹¹	36	2.5 μs	p-p	TOTEM (7 TeV)	1100 m	1.0×10 ²⁸
				TOTEM (.9 TeV)	150 m	1.0×10 ²⁸
<i>(g) Ion runs</i>						
7×10 ⁷	1		Pb-Pb	ALICE/ATLAS/CMS	0.5 m	1.7×10 ²⁴
7×10 ⁷	592		Pb-Pb	ALICE/ATLAS/CMS	0.5 m	1.0×10 ²⁷

Ions:

Initial peak luminosity is low: $1.7 \times 10^{24} \text{ cm}^{-2} \text{ s}^{-1}$

Large cross-section Pb-Pb will produce high event rates for luminometers.

Range of machine conditions:

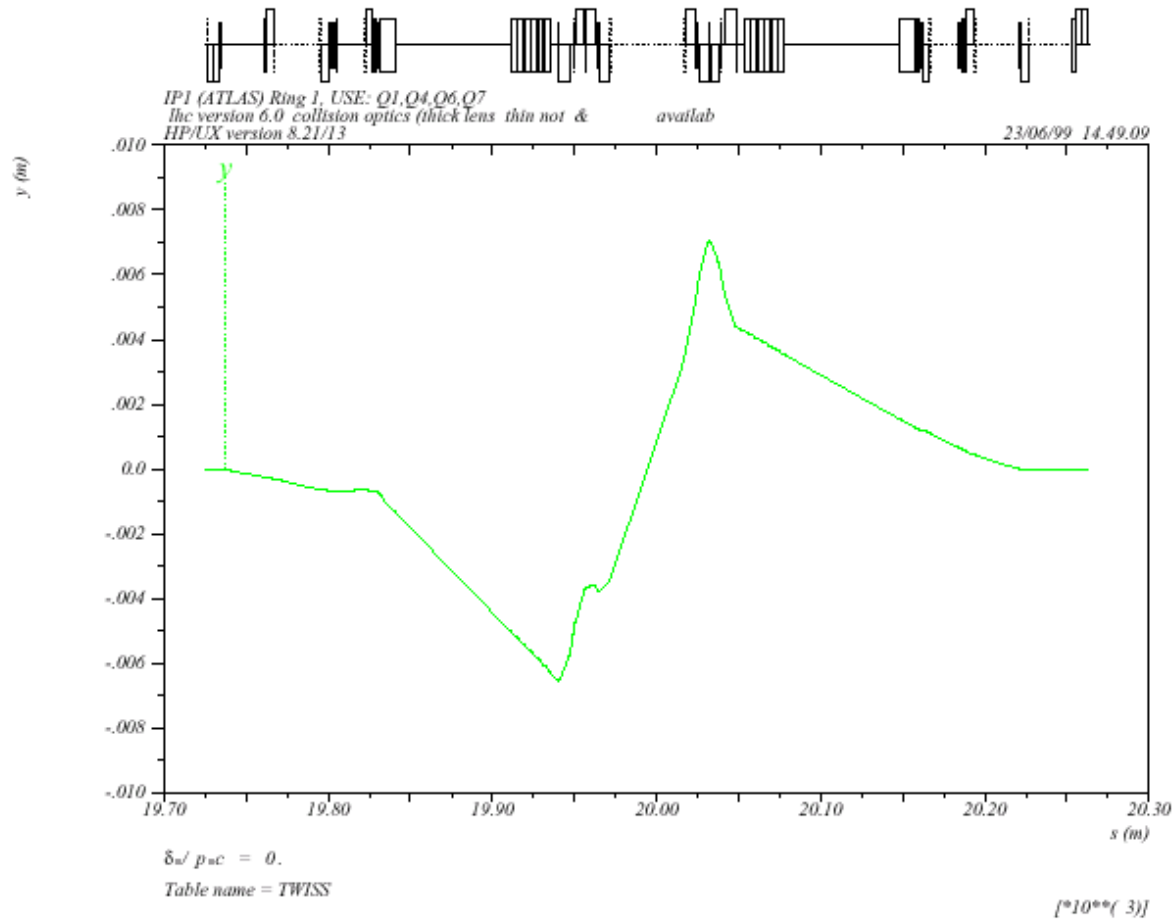
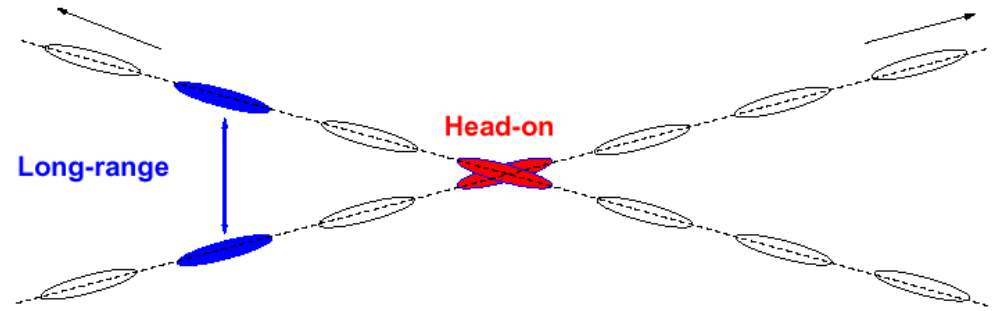
(a) Ranges in crossing angles

IR	Experiment	IP beta	Crossing angle plane	<u>Half total crossing angle</u>	Range for nominal cases
1	ATLAS	0.5 m	Vertical	$\pm 150 \mu\text{rad}$	
2	ALICE	10 m	Vertical	$\pm 150 (80) \mu\text{rad}$	$\pm(35-150) \mu\text{rad}$
5	CMS	0.5 m	Horizontal	$\pm 150 \mu\text{rad}$	
5	TOTEM	1100 m	Horizontal	$0 \mu\text{rad}$	
8	LHC-B	35 m	Horizontal	$\pm 285 (150) \mu\text{rad}$	$\pm(200-285) \mu\text{rad}$

Table 2: Magnitude and plane of the total crossing angle for nominal LHC. In brackets the contribution from the external orbit bump is listed for IR2 and IR8.

Luminometer must cope with crossing angle range from 0 to maximum (sign of slope at IP must be assumed to be free).

Beam-beam crossing: *W. Herr et al*



Anticipated uses:

(a) Initial beam finding and overlap optimization

BPM's at IP: $\Delta y \text{ (IP)} \sim \text{sqrt}(2) * \delta_{\text{res}}$

BPM resolution	$\Delta y \text{ (IP)}$	in sigma	β^*	
200 μm	283 μm	18 σ	0.5 m	Low
200 μm	283 μm	3 σ	18.0 m	Int
50 μm	70 μm	4.4 σ	0.5 m	High
50 μm	70 μm	0.7 σ	18 m	Int

Required luminosity measurement to go further:

L resolution $\sim 1 \times 10^{28} \text{ cm}^{-2} \text{ s}^{-1}$
Time response **Minutes**
Accuracy **10 %**

(b) Luminosity optimization (and re-optimization at start of physics)

L resolution	1% for full beam
L reproducibility	1 %
Time response	1 s

(c) Luminosity feedback

L resolution	1% for full beam
Time response	1 s

(d) Luminosity equalization between experiments

Absolute L accuracy	given by experiments
L reproducibility	1 %
L resolution	1 % for full beam
Time response	uncritical

(e) Minimization of beam-beam excitation

Allowed beam-beam offsets	0.2 σ
L resolution	1 % per bunch
Time response	minutes

$$L \approx L_0 \cdot e^{-\left[\Delta y_{IP}^2 / (2\sigma_y^*)^2 \right]}$$

(f) Monitoring of crossing angle

Luminometers might provide estimate of crossing angle. This is desirable, if device remains robust!

Desired angle accuracy **7 μrad**

(g) Monitoring of vertex position

Experiments

(h) Bunch-by-bunch measurements

Desirable for various multi-bunch studies (see also e)

L resolution

few % to 10 % per bunch

Time response

minutes

(i) Monitoring of background

Bunch-by-bunch?

Signal every second?

Resolution 1-10%?

Machine-Experiment Information exchange:

Entity	Detail
Spectrometer Magnets	Currents and polarity
Position of Moveable Detectors Components	LHCb Vertex Detector (VELO) TOTEM Roman Pots
Background Measurements	Spatial and temporal distributions
Beam Characteristics	Vertex position (x,y,z) Luminous region
Absolute and Instantaneous Luminosity	Various sources for instantaneous (calorimeter currents, dedicated counters) TOTEM for absolute

The **vertex position** is measured in the reference frame of the experiment.

A **conversion** to the machine reference frame shall be done before transmission.

It will be based either on survey data measured during shut-downs or on continuous monitoring wherever available.

The **relative luminosity** can be measured from trigger rates and both the **integral/average and bunch-by-bunch values** will be provided.

Transmission of the summary information from the experiments to the machine can be performed at least **every minute**.

The **bunch-by-bunch luminosity** can be reported at a rate of **1 Hz**.

The expected **accuracy is of the order of a few per cent**.

The same detectors are planned to measure the **backgrounds** and would deliver the data **at the same rate**.

Machine to experiments:

Relative luminosity, as useful.

General information on machine status (Page 1).

Logging database of all machine measurements.

Conclusions

We are at the end of the collection of the requirements.

The issue of whether the background monitors are included is to be settled.

The next step is the to go from requirements to functional specifications.

This should be well advanced or ready by Xmas.